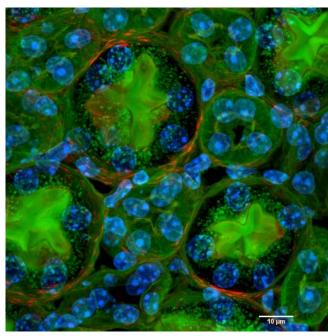
Imaging Beyond the Basics: Optimizing Settings on the Leica SP8 Confocal



Todays Goal:

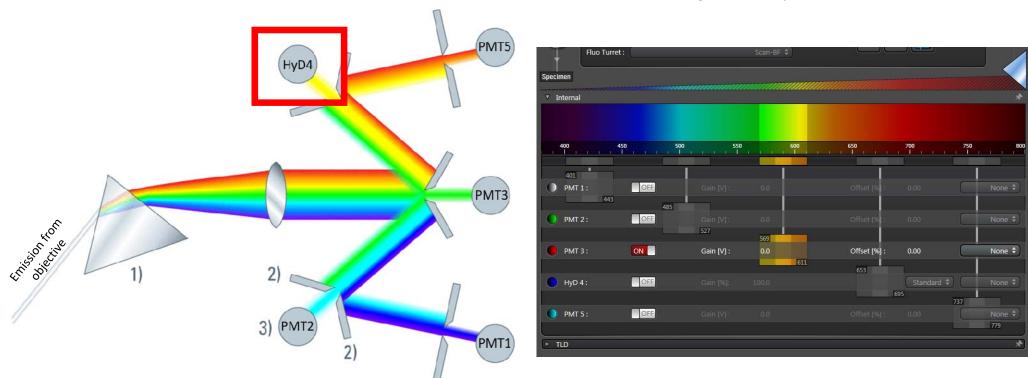
Introduce some additional functionalities of the Leica SP8 confocal

- HyD vs. PMT detectors
- Dye Assistant
- Scanning "By Frame" vs. "By Line"
- Bi-directional and resonant scanning
- Optimizing resolution and pixel size
- Using the Histogram and QuickLUT
- Linear Z compensation



Spectral Detection with the Leica SP8

- Light emitted from the sample passes through a prism
- There are 5 detectors in the scan head
- Movable slits and mirrors in front of the detectors determine what wavelengths are captured



PMT vs. HyD Detectors

Photomultiplier tubes (PMT): <u>Detectors 1,2,3,5</u>



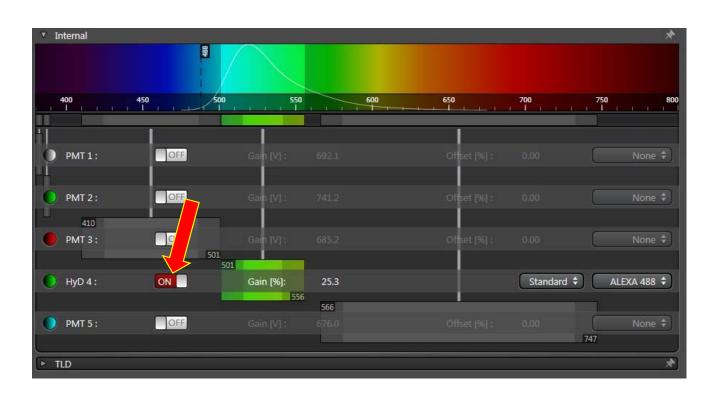
- Convert photons to photoelectrons
- Low sensitivity (30% QE)
- Inexpensive

Hybrid Detector (HyD) <u>Detector 4:</u>



- Cross between PMT and APD
- More sensitive (45% QE) Use for low light applications
- Lower Noise
- Expensive
- Can be damaged

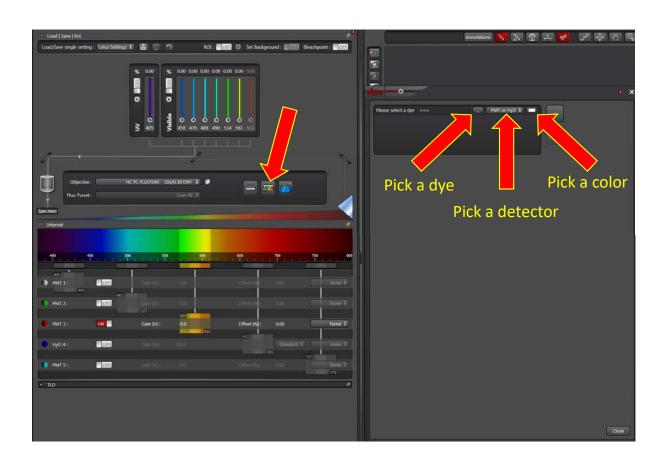
Using the HyD Detector on the SP8



- Auto shutoff will engage if HyD is exposed to too much light
- Start with low laser power and gain
- Gain is in % (not V)

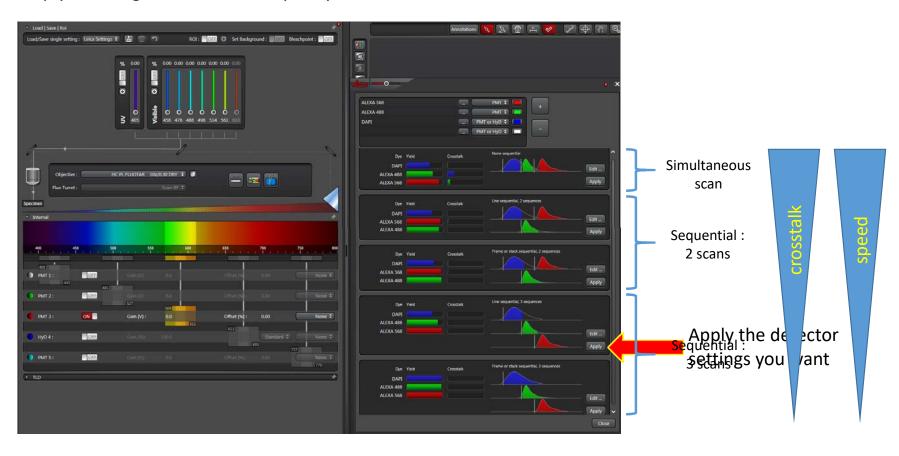
Dye Assistant

• A wizard to help you configure the excitation and detection settings quickly



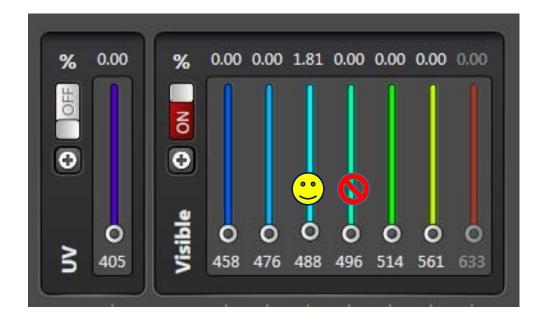
Dye Assistant

A wizard to help you configure the detector quickly



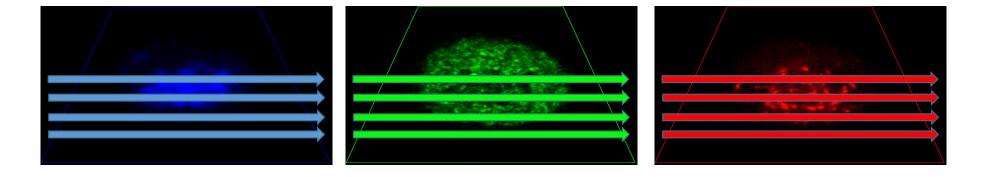
Dye Assistant Note

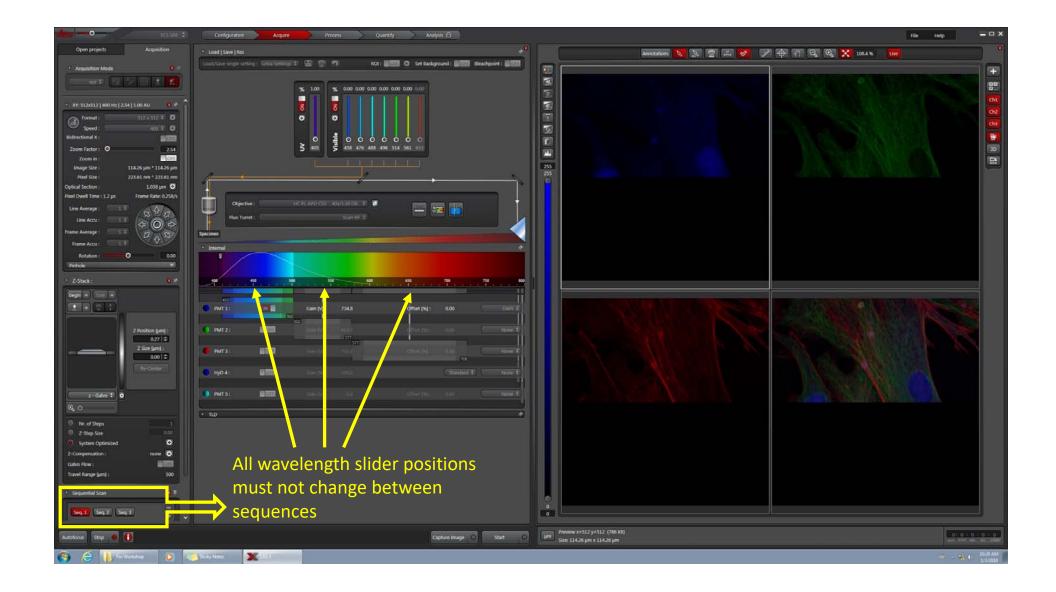
- The Wizard will choose the 496 nm laser for Alexa 488
- While 496 nm is closer to the actual excitation peak of Alexa 488...
-The 488 nm laser is much stronger
- You will have to manually choose 488 nm excitation for this channel



Scanning Sequentially "By Line"

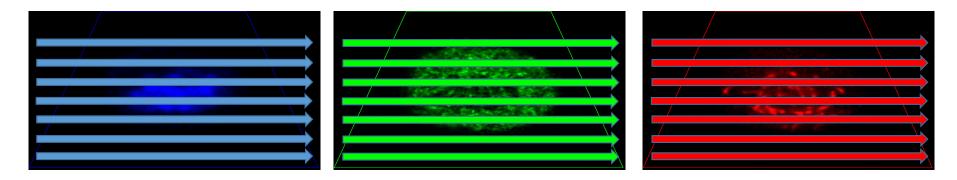
- Scans 1 line of each channel, one after the other
- All channels will appear to be captured simultaneously
- Wavelength sliders <u>cannot move</u> between channels during this type of scan NO MOVING PARTS
- Fastest method of sequential scanning
- Slightly less photon efficient than "By Frame"



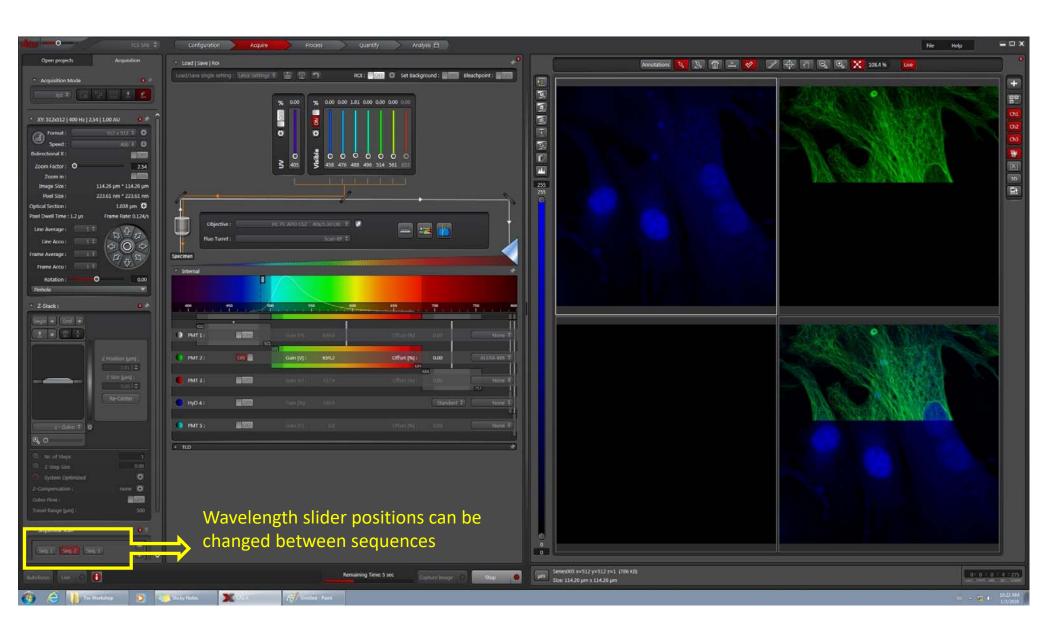


Scanning Sequentially "By Frame"

- Scans entire image of one channel before moving to the next channel
- All channels will be captured one by one
- Wavelength sliders <u>can move</u> between frames during this type of scan –MOVING PARTS
- Slowest method of sequential scanning
- More range/flexibility in setting emission bandwidth, more photon efficient



One application would be to use the HyD detector for multiple channels



Acquisition Speed Comparison

- 400 lps scan speed
- 512 x 512 pixels
- 3 channels
- 10 um z range, 30 planes

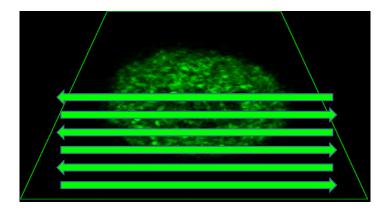
By Frame	By Line		
3 min 46 sec	1 min 52 sec		

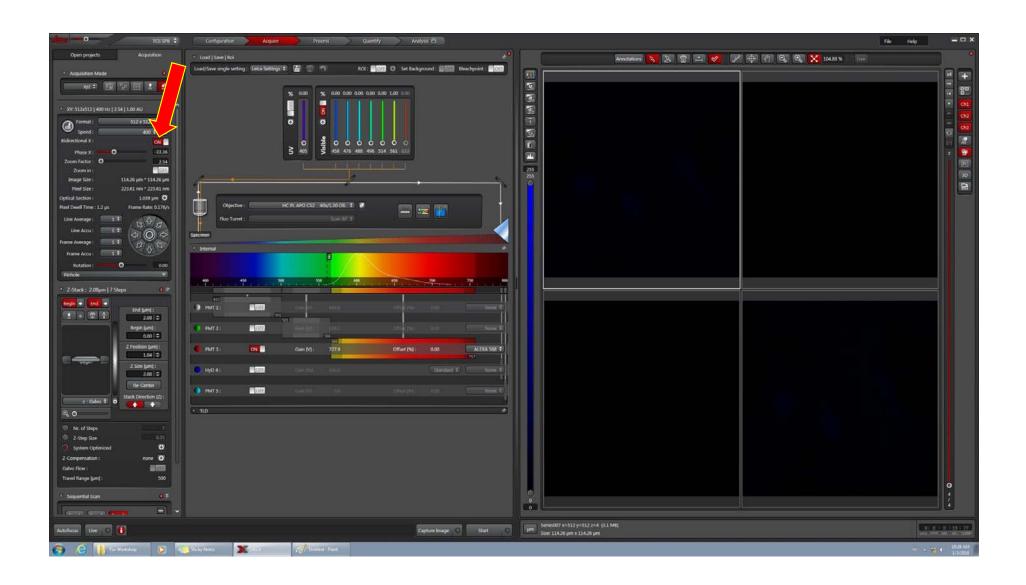


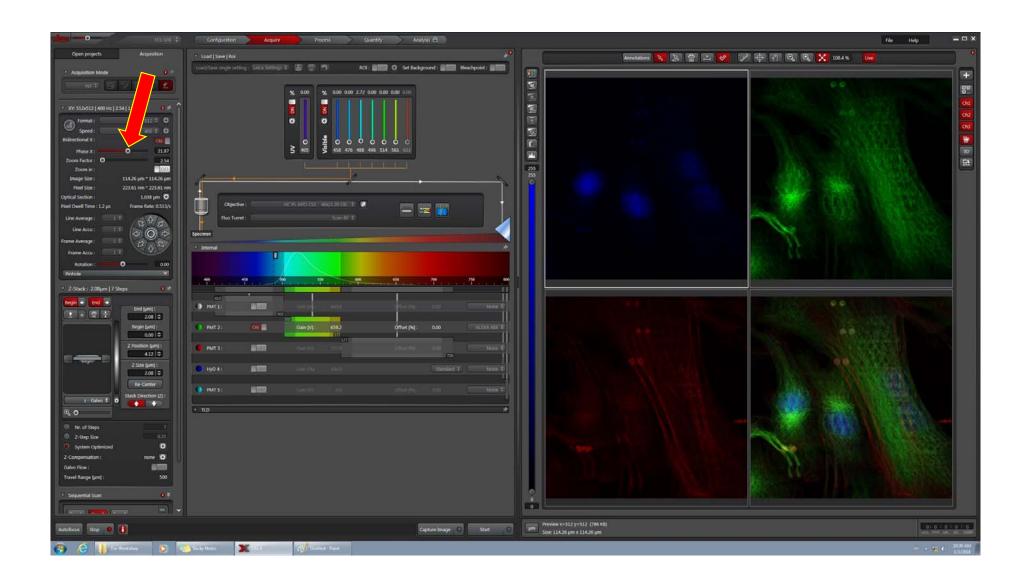
"Between Stacks" not recommended

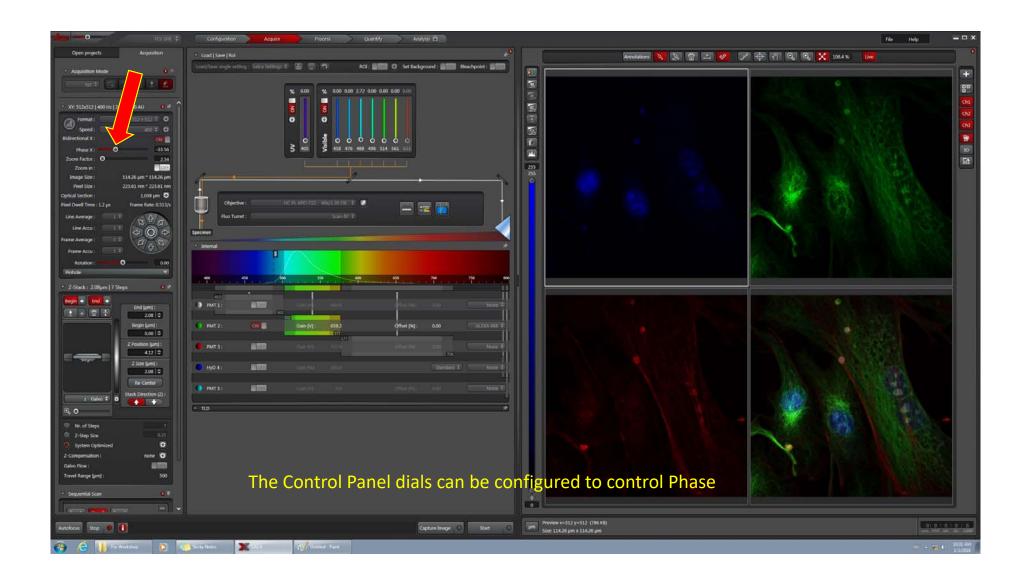
Bi-Directional Scanning

- Capture is usually done in only one direction of the beam scan
- Imaging can also be done on the return pass of the beam
- 2X as fast
- Reverses the direction in which pixels are recorded
- Alignment of the scan phase is needed









Acquisition Speed Comparison

- 400 lps scan speed
- 512 x 512 pixels
- 3 channels
- 10 um z range, 30 planes

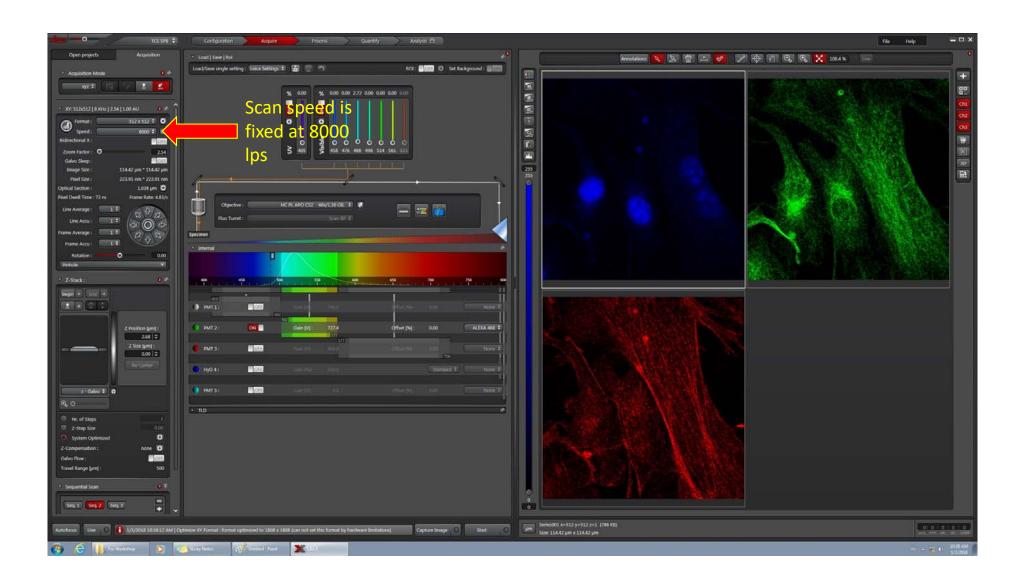
By Frame		By Line + Bidirectional	
3 min 46 sec	1 min 52 sec	56 sec	

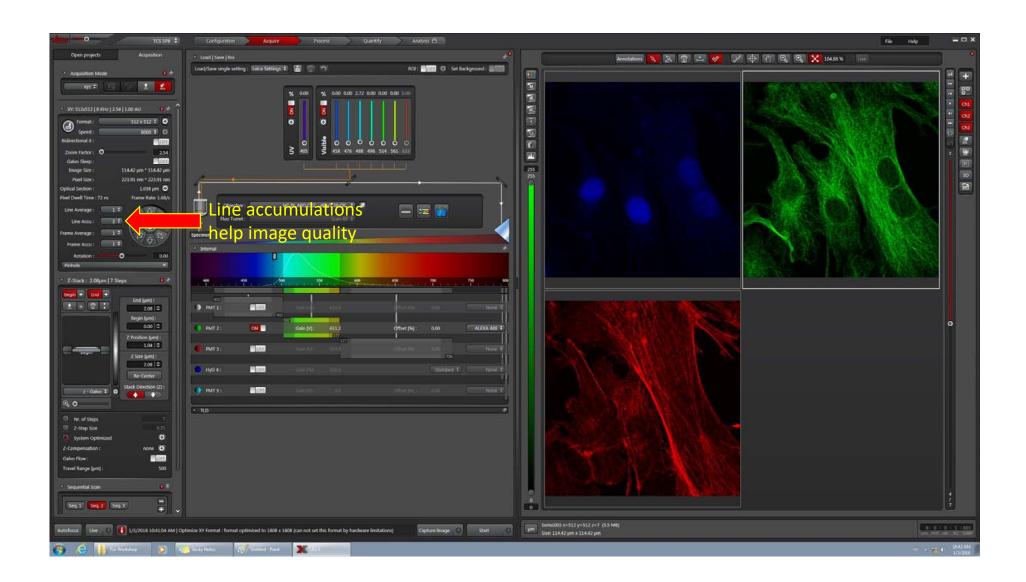
Resonant Scanning for large samples

- The excitation beam is usually raster scanned by the movement of galvanometer driven mirrors *flexible scan speeds but slow*
- These can be replaced by faster "resonant" scanning mirrors which oscillate more rapidly, - fast but fixed scan speed
- Select Resonant "On" at Startup









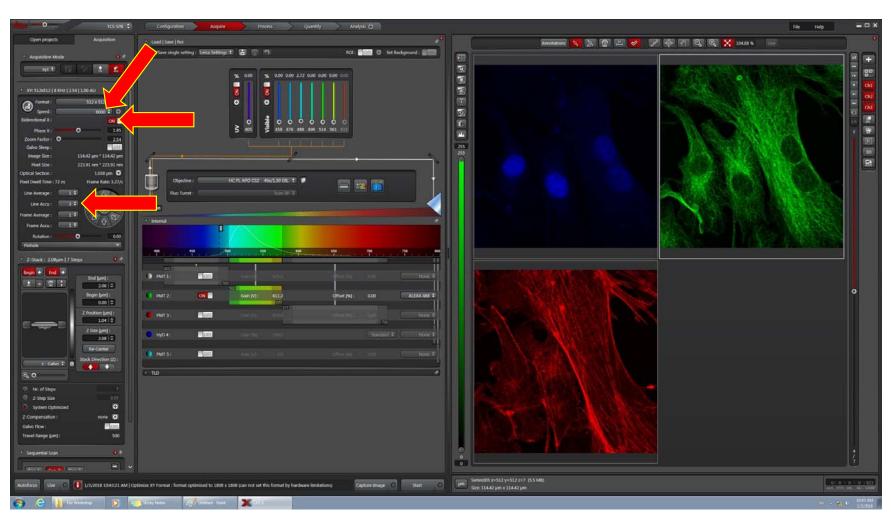
Acquisition Speed Comparison

- 400 or 8000 lps scan speed
- 512 x 512 pixels
- 3 channels
- 10 um z range, 30 planes

By Frame			By Line + Resonant*	
3 min 46 sec	1 min 52 sec	56 sec	17 sec	

*w/3 line accumulations

Combining "By Line" + Resonant + Bi-directional



Acquisition Speed Comparison

- 400 or 8000 lps scan speed
- 512 x 512 pixels
- 3 channels
- 10 um z range, 30 planes

25X Faster!

By Frame	By Line	By Line + Bidirectional	Resonant*	By Line + Resonant* + Bidirectional
3 min 46 sec	1 min 52 sec	56 sec	17 sec	9 sec

^{*}w/3 line accumulations

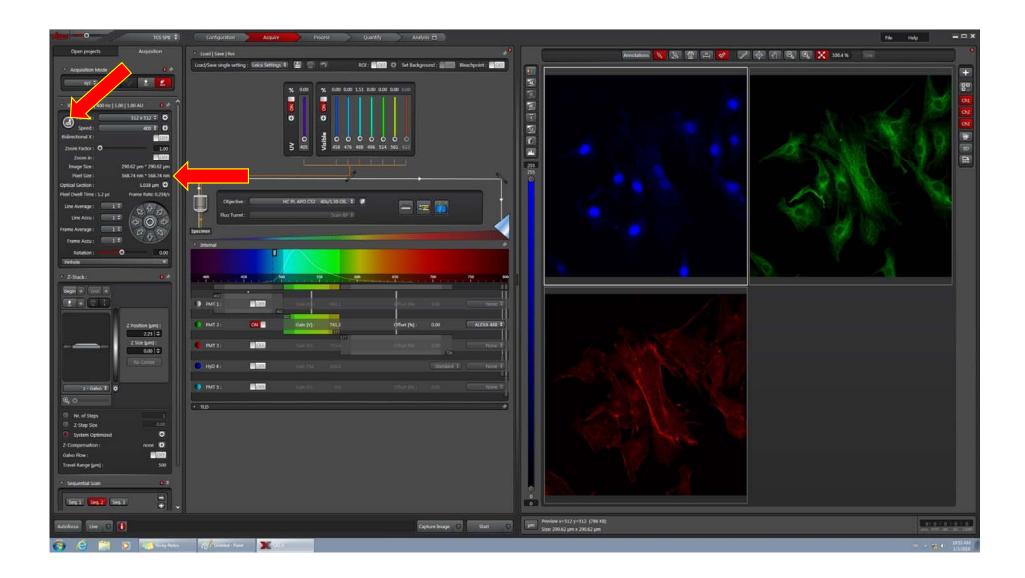
Optimizing Resolution and Pixel Size

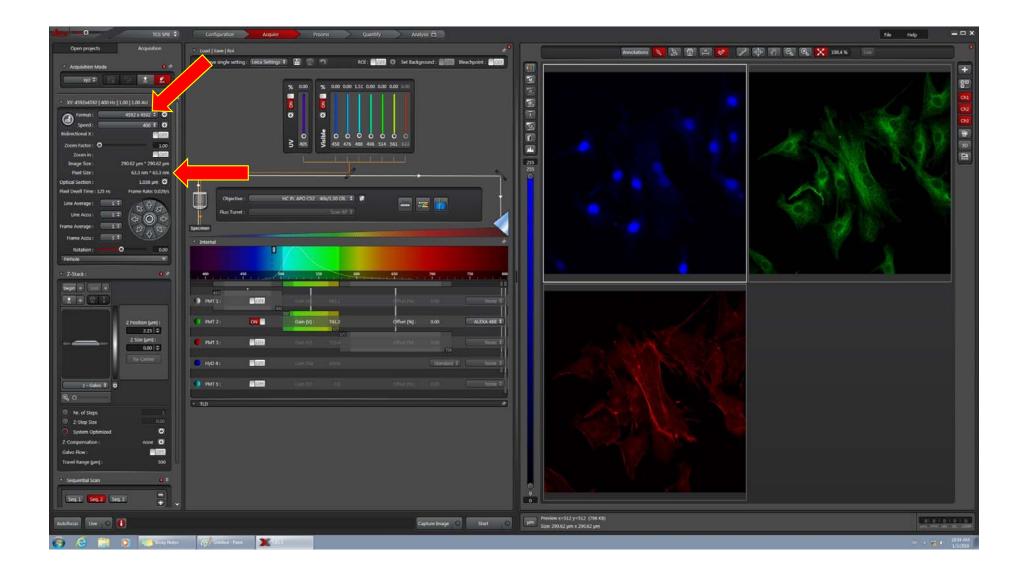
- Each objective lens is capable of achieving only so much resolution
- The pixel size of the image must be set properly to achieve the max resolution (lens resolution / 2.3)
- There are two ways to do this:
 - 1. Increase zoom factor
 - 2. Increase the number of pixels
- The software has a button that will increase the number of pixels to maximize resolution for a given lens

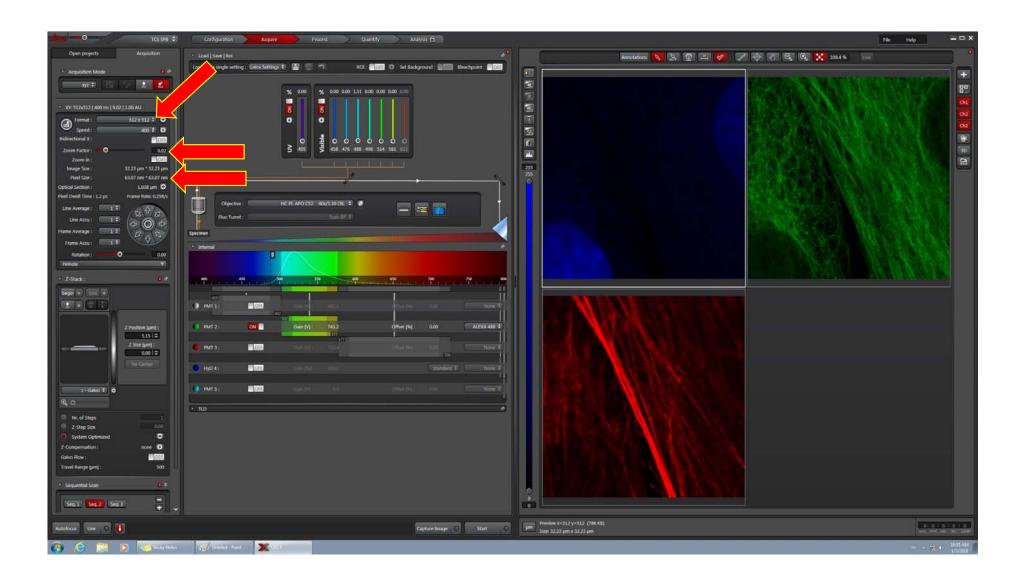
Zoom Factor: O

- However, more pixels take longer to scan
- Pixels smaller than theoretical best size have no additional benefit







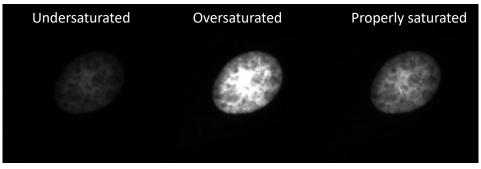


Optimizing Images with the Histogram or Quick LUT

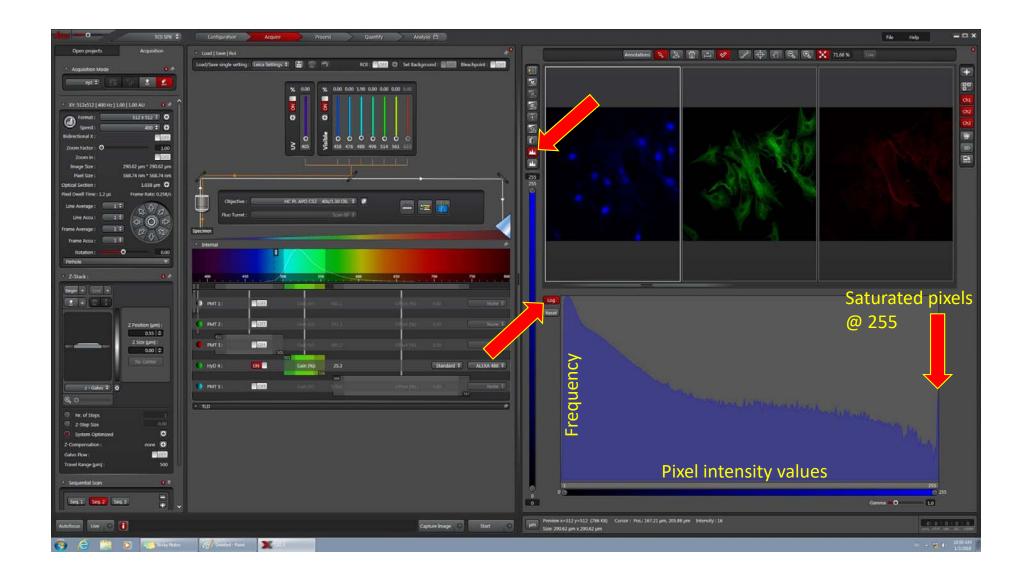
"Your eyes can deceive you. Don't trust them."
-Obi-Wan Kenobi

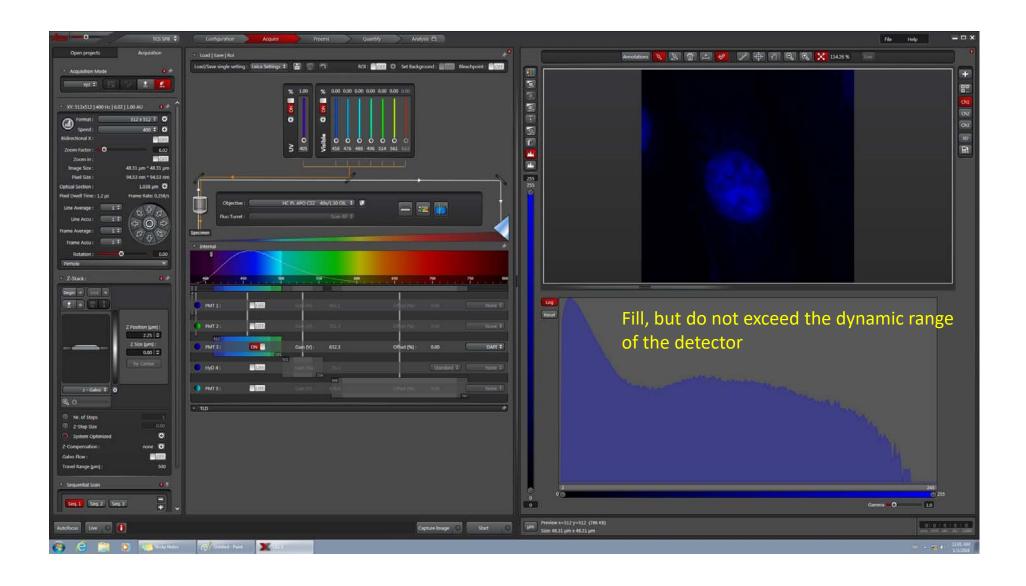


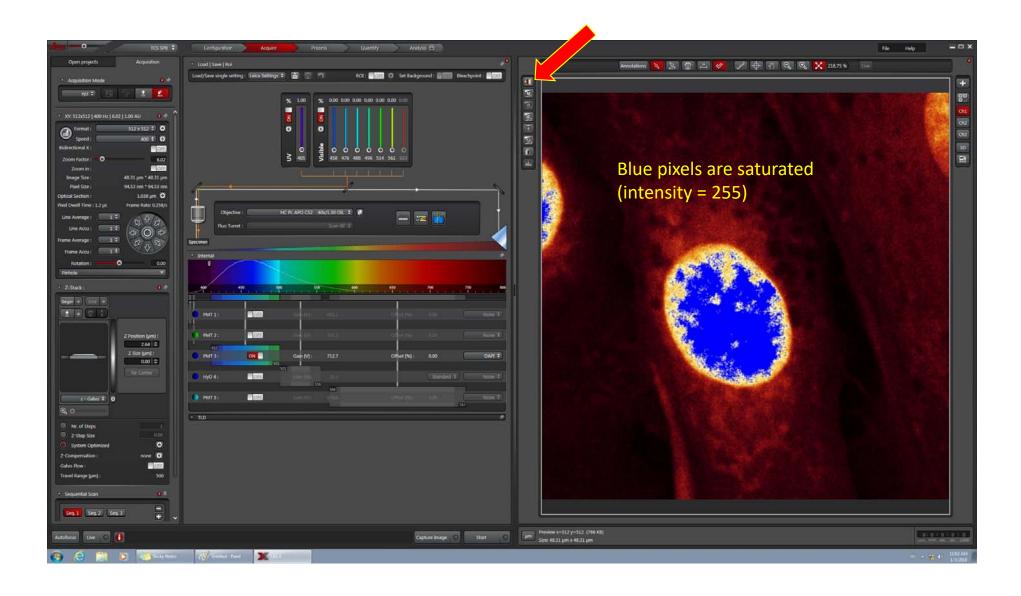
 Images which are under or oversaturated are not using the dynamic range of the detector

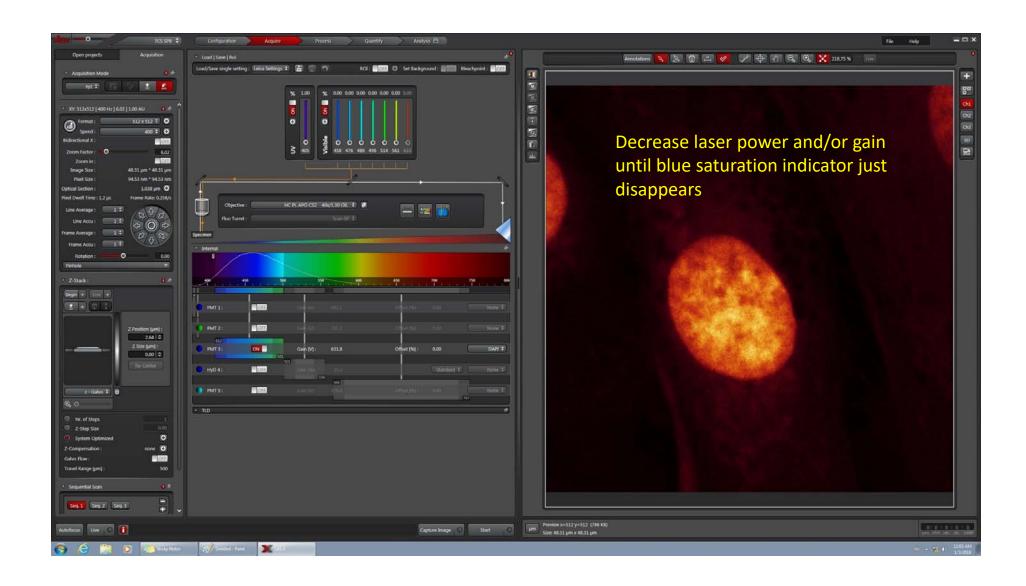


- These images are missing information
- There are quantitative tools to help you choose the best laser power and gain



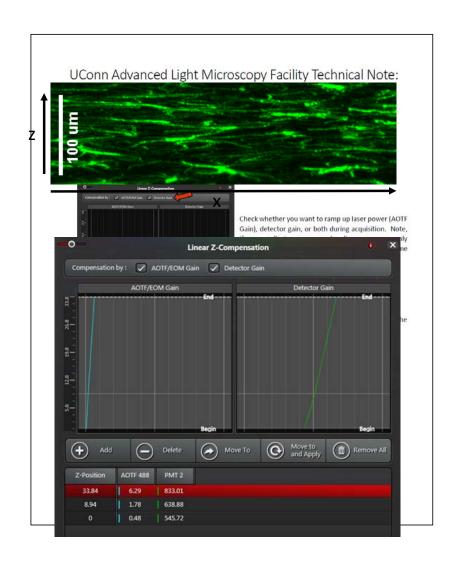






Linear Z Compensation

- Optical aberrations get worse the deeper you image into a specimen
- One result is decreasing signal during z stacks (usually noticeable > 20 um)
- Laser power and gain can be automatically increased as a function of depth to help keep intensity constant through the sample
- confocal.uconn.edu/resources/



120 um z stack through mouse hippocampus

